

More Dexterity, More Possibilities





A1 Standard

- Equipped with smart camera (Depth camera)
- Support real-time HD video transmission
- Secondary development (High-level and low-level real-time API)
- Human follow, Body recognition, Depth perception
- Multiplayer mode (Battle mode), Group control



A1 Explorer (With all the functions of A1 standard)

- Optional Lidar:

Dynamic obstacle avoidance Navigation planning

Map construction

Autonomous positioning

- Optional AI module etc. :

Skeleton recognition, Gesture recognition, Visual SLAM
Professional secondary development (Machine learning, Reinforcement learning etc.)

ROBOT

- Machine Weight (with battery): 12kg
- Dimensions (Stand): $500 \times 300 \times 400$ mm(L×W×H)
- Dimensions (Folded): $450 \times 300 \times 150$ mm(L \times W \times H)
- Maximum Walking Speed: 3.3m/s
- Operating Time: 1-2.5h
- Real-time HD video transmission: 0.1-0.2s delay
- 12 DOFS
- Payload: 5kg
- Abundant External Interface: $HDMI \times 2$, $FE \times 2$, USB 3.0×4

MOTOR

- Joint torque: 33.5NM
- Joint maximum speed: 21 rad/sJoints support quick disassembly
- and easy maintenance
- Read all sensor data
- Send position, speed and torque commands to each motor

SUPPORT FUNCTION

- 3 Protection Modes: Emergency stop, Fall protection, Overheat
- 4 Warning Systems:
 Low voltage, High temperature
 Short circuit, Overcharge
- 2 RTOS:

Motion control: Ubuntu Environmental awareness: Ubuntu-ROS

- 4 Foot Froce Sensors:
 Get the foot support imformation directly,
 more reliable, efficient and convenient
- Power Outputs: 5V, 12V, 19V

APPLICATION

- Research and STEM
- Entertainment
- Security and Inspection
- Exploration and Rescue
- Express and Logistics
- Care

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